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**APPARATUS FOR MANUFACTURING TOY**

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Inventor(s): SAKURAI HOSHIMITSU; others: 01  
Applicant(s): BANDAI CO  
Requested Patent: JP62050112  
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EC Classification:  
Equivalents: JP1778433C, JP3049732B

**Abstract**

**PURPOSE:** To carry out successively the insert molding of a plurality of constituting parts, by providing a stripper set on a rotary shaft in freely sliding and rotating manner for holding a part of the runner of the parts molded in between a core and a cavity constituting a mold and for transferring it to the mold of the next molding order.

**CONSTITUTION:** The cavity 1 and the core 2 are tightly contacted and the parts 1c having being molded in the former order and being connected to the runner 1a are loosely inserted in the mold. Through injection molding into the same mold under this condition, a part of the part 1c having been molded in the former molding process is monolithically insert-molded with a part 1d molded in the latter order. The cavity 1 is then separated from the core 2 side and a projected plate 5 and monolithically molded parts 1c, 1d are thereafter separated with a stripper 4. They are transferred to the next molding process by being holded by the stripper 4 and the post forming is successively carried out.

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審査請求 未請求 発明の数 1 (全5頁)

⑭ 発明の名称 玩具の製造装置

⑮ 特 願 昭60-190484

⑯ 出 願 昭60(1985)8月29日

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明 細 書

である。

# 1. 発明の名称

玩具の製造装置

# 2. 特許請求の範囲

回転軸を中心として同心円上に夫々所定角度を有して複数の成形型を配置するとともに、夫々の成形型には予め定められた成形順位に従って、夫々個別部等を構成するための対応する部品の位置に所望の型を形成してなり、かつこれらの成形型を構成するコア側とキャビティ側の間には成形される部品のランカの一部を保持して次の成形順位の成形型に移送するための上記回転軸の軸方向に回転自在、ならびに回転自在に設置したストリッパを設けてなることを特徴とする玩具の製造装置。

# 3. 発明の好適な説明

「産業上の利用分野」

本発明は人間形を有した玩具の製造装置に関し、とくに人形の関節部を含む胴部、脚部、腕部等の主要の構成部品を連続する複数の成形工程によって一体成形を可能とする製造装置を提供するもの

「従来の技術」

従来の人形の製造装置は人形の頭部、胴部、脚部の各構成部品を合成樹脂の成形等により、夫々前後もしくは左右の分割部品として成形するのである。これらの部品は人手による組立工程によって夫々ビス止めによって組合し、さらにリベット止め等によって相互の部品を回転自在に連結することによって所要の人間部を形成していた。

「発明が解決しようとする課題」

しかし上記従来の製造装置によると、人形の胴部、脚部、腕部等の各構成部品を夫々前後もしくは左右の分割部品として成形しているので、例えば最も控えめに計算しても胴部で5個、脚部で5個×2=10個、腕部で4×2=8個からなり、これらの成形部品が計23個、組立のためのビス8個、リベット8個等により、人形を一体組立するのに少なくとも最少39個の部品が必要で、極めて多くの部品点数が必要である等の欠点を有し、またこれら人形の関節部等の相互に滑動した成形部品

は成形時の収縮率によって、定められた成形条件の下で均一に成形されることは困難である等の欠点を有し、さらにこれらの部品は人手によって一々組立てい ので組立が極めて面倒であり、組立工数が多かかるとともに各工程の品質管理を充分行なったとしても上記成形上の問題とも関連してどうしても仕上り製品にバラツキが生じ、製造コストが高価となる等の欠点を有していた。

「問題を解決するための手段」

本発明は上記従来の製造装置による製造上の欠点を除去するもので、回転軸を中心として同心円上に夫々所定角度を置いて複数の成形型を配置するとともに、夫々の成形型には予め定められた成形位置に於いて、夫々個部部等を構成するための対応する部品の位置に所定の型を形成してなり、かつこれ等の成形型を構成するコア側とキャビティ側の間には成形される部品のランナの一部を保持して次の成形位置の成形型に移送するための上記回転軸の軸方向に回転自在、ならびに回転自在に配置したストリップを設けてなるものである。

一方の部材となる突出部27a、27bを具えた部材27を形成している。つぎに第3の成形工程において図面Cの様に上記突出部25aと突出部27aを夫々回転自在に包持する軸受部材28と、同じく突出部22aと突出部27bを夫々回転自在に包持する軸受部材29をインサートにより一体的に成形している。

かかる成形工程において後述位となる第2の成形工程の成形部品はその先期位となる第1の成形工程に用いられる成形部材よりも断面積が低く、収縮率の大きい成形部材を用いて成形される。またこれよりも後述位となる第3の成形工程の成形部品はその先期位となる第2の成形工程に用いられる成形部材よりも断面積が低く、収縮率の大きい成形部材を用いて成形され、これらのインサート成形を含む成形工程が順次連続的に行なわれることによって、上記複数の個部部を部材20等の主要な構成部品を一体的に成形している。

第2図は上記一連の成形工程を行なうための成形装置のコア2側の要部正面図であって、回転軸

「実施例」

以下図に示す一実施例について本発明を説明すると、第6図、第7図は本発明の実施例において製造しようとする人形であって、この人形は個部部を含む主要な構成部品として図部10、脚部20、腕部30からなり、また図部10は夫々回転自在に連結される頸部11、胴部12、腰部13等からなる。

かかる人形の製造工程において、第5図に示す一方の脚部20の製造過程に基いて説明すると、まず第1の成形工程において第5図Aの様にランナ1aに連なり上記図部13の軸受部14に装着するための軸21aを突設した軸部材21と、図部部を構成する一方の部材となる突出部22aを具えた足部22と、補強部材23、24を成形している。つぎに第2の成形工程において図面Bの様にランナ1aに連なり、上記軸部材21を回転自在に包持するとともに他方に突出部25aを具えた中間部品25と、上記突出部22aを回転自在に包持するとともに他方に突出部26aを具えた中間部品26を夫々インサート成形し、かつその中間には頸部の個部部を構成する

3を中心として同心円上の位置Xに上記第1の成形工程に用いられる第1の成形型1xを設け、図型1xより120°回転した位置Yに上記第2の成形工程に用いられる第2の成形型1yを設け、図成形型1yよりさらに120°回転した位置Zに上記第3の成形工程で用いられる第3の成形型1zを夫々設けている。かかる成形型には予め定められた成形位置に於いて、夫々個部部等を構成するための対応する部品の位置に所定の型を形成している。

第1図は上記成形装置の要部分解斜視図であって、図面において1は上記コア2に対応する成形型のキャビティで、図キャビティ1と対向するコア2の間には上記の様に成形される部品を次の成形位置にある成形型に移送するための移送手段として、上記回転軸3を具え回転自在ならびに軸方向に移動自在に上記ランナ1aの一部を保持するストリップ4を装着している。またコア2の間には突出しピン3aを具えた突出し台5を設け、これらコア2方より突出し台5は加圧装置に連なる押圧台6に突設した複数のガイドピン6aに沿ってス

アリング60を介して軸方向に回転自在に設置している。また上記回転軸3にはこれを所定角度、すなわち上記120°づつ回転するための三方に突出した係合爪7を設け、その外側にはこれを回転自在に保持するとともに一個に油圧装置8を具えた室内枠8を設置し、同室内枠8内に油圧装置のピストン軸に活動自在に設置した作動軸9を油圧側に上記係合爪7に接続するための半月状の室内溝槽を形成している。

#### 「作用」

以上の様な成形装置を用いた成形工程の各部の動作を図3図および第4図に於いて説明すると、この場合、第3図のaにおいてキャビティ1側にコア2側が配置しており、かつその型内には先順位の工程において成形された部品1cがランナ1aに達した形で留められており、この状態で同型内に併出成形することによって後順位の成形部品1dによって先順位の成形工程の部品1cの一部を一体的にインサート成形することができる。つぎに同図bの様にキャビティ1が、コア2側より離れ、

様に併出成形が行なわれる。

以上の様な動作の繰返しによって各成形型において夫々連続的に成形が行なわれる。しかして第2図における位置xの成形型1aで成形された部品は上記ストリップ4の回転とともに位置yの成形型1bに案内されて中間部品等がインサート成形され、さらにストリップ4の回転とともに位置zの成形型1cに案内されて残りの部分が一体的にインサート成形され、最終的に同部品を含む主要な構成部品の完成品として取出される。またこれとともに各ランナーは図示省略のランナー切除装置によって成形部品から切除される。

#### 「発明の効果」

以上の様に同部品等を構成するための一方の部品を形成する先順位の成形工程と、同部品と対となる他方の部品を形成する後順位の成形工程等からなる複数のインサート成形工程を連続的に行なうことにより、例えば実施例の様な同部品を含む人形の胴部、足部、腕部等の主要な構成部品を夫々一々成形することができる。これによって従来

さらに同図cの様に油圧装置の油圧動作によって油圧台6、回転軸3を介してストリップ4とともに突出し台5と一体の突出しピン5aが突出され、同ストリップ4と一体に上記成形部品1c、1dがコア2側の型から離される。つぎに第4図のdの様に引き抜きストリップ4が押出されると、突出しピン5aがとり残された形となり、同ストリップ4は突出しピン5aから離れて回転可能な状態となる。つぎに同図eにおいて上記油圧装置8が作動して上記作動軸9、係合爪7、回転軸3を介して同ストリップ4は所定の角度、即ち120°回転されることによって、この位置の型で成形された上記成形部品1c、1dは同ストリップ4に保持された状態で後順位の工程の成形型上に移動する、一方上記と同様に先順位の工程で成形された新たな成形部品1cがストリップ4の回転とともに送られて同型上に位置する。つぎにfの様に上記油圧装置が後退してストリップ4がコア2側に位置するとともに上記先順位の工程の成形部品1cを型上に戻過して配置する。以下上記第3図のaの状態となり同

型の様に多くの部品を一々成形して組立する必要がなく、部品点数ならびに組立工程を大巾に削減し、製造コストを大巾に低減することができる。

とくに回転軸を中心として同心円上に夫々所定角度において複数の成形型を配置し、夫々の成形型には予め定められた成形部品に於いて所定の型を形成しているの、上記回転軸の軸方向に回転自在ならびに回転自在にストリップを設け、その上下動と回転動の2段階動作を伴う簡単な移送手段によって、夫々の位置で成形される部品のランナーの一部を保持して正確に次の順位の成形型に移送することができ、これによって複数のインサート成形を連続的に行なう成形装置を簡易化するとともに常に安定した動作をもって成形を可能とするものである。

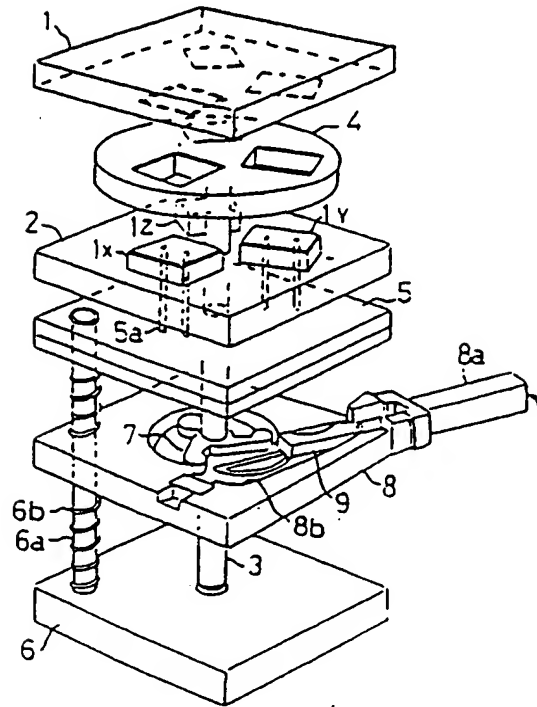
さらに上記の様に複数の連続するインサート成形によって、従来の様な成形上の不具合による製品のバラツキがなく常に品質の安定した完成品を提供することができる。

#### 4. 図面の簡単な説明

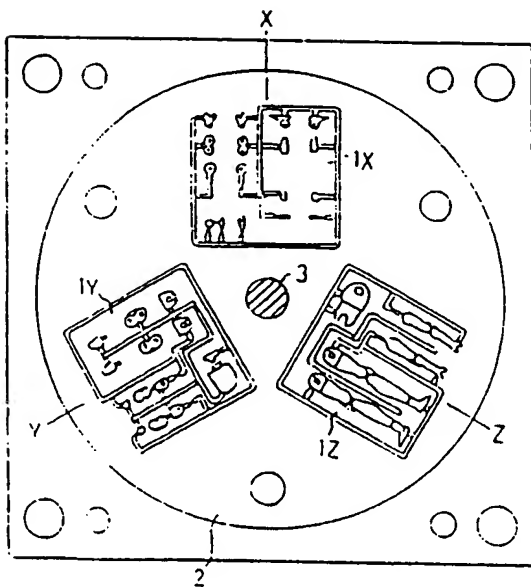
第1図は本発明の一実施例を示す玩具の製造装置の要部分解斜視図、第2図は同じく成形装置の要部平面図、第3図、第4図は同じく成形工程における各部の動作説明用成形装置の要部側面図、第5図は同じく人形の脚部の各成形工程の説明用斜視図、第6図は人形の要部切欠正面図、第7図は同じく人形の要部切欠側面図である。

図中、1はキャビティ、2はコア、3は回転軸、4はストリップ、5は突出台、6は圧台、7は係合爪、8は案内棒、9は作動棒、1xは第1の成形型、1yは第2の成形型、1zは第3の成形型、1a、1bはランナ、1cは脚部、2aは脚部、3aは脚部である。

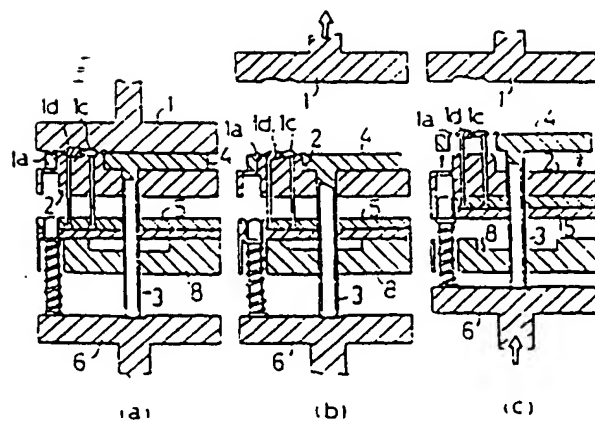
特許出願人 株式会社バンダイ



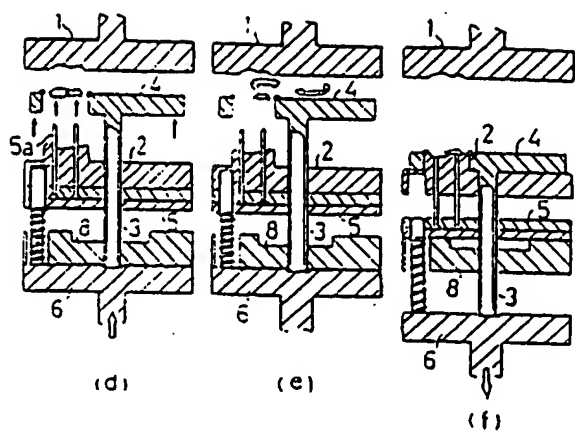
第1図



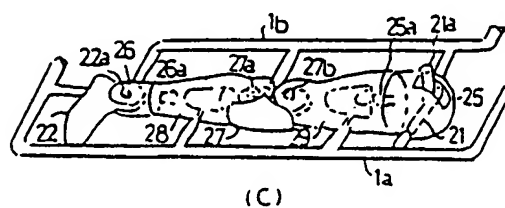
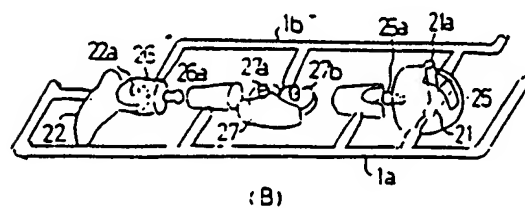
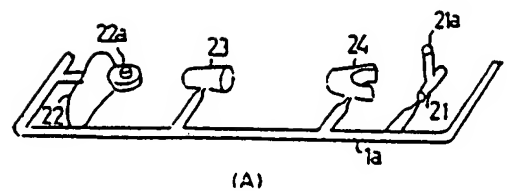
第2図



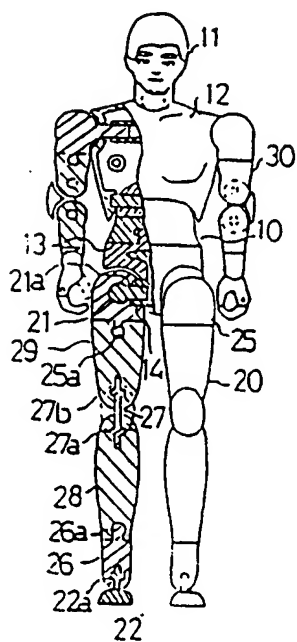
第3図



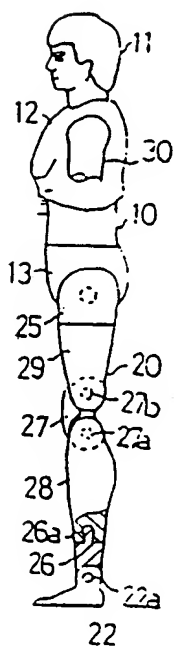
第 4 図



第 5 図



第 6 図



第 7 図

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(54) Title of Invention Device for Manufacturing Toy

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## **Specification**

### **1. Title of Invention**

#### **Device for Manufacturing Toy**

### **2. Scope of Patent Claim**

A device for manufacturing a toy in which multiple molding dies are disposed, with various indicated angles in between, on concentric circles centered on a rotating shaft; at the same time, an indicated die is formed at the position of the corresponding components to form respective articulating parts according to a predetermined formation sequence on the respective formation dies; a runner part for the component is formed between a core side which makes up this and other formation dies and a cavity side; it also has a stripper which allows it to turn freely in the shaft direction of the aforementioned rotation shaft so that it can move to the next formation sequence.

### **3. Detailed Description of Invention**

#### **[Industrial Field]**

The present invention relates to a device for manufacturing toys which is provided with an articulated part and in particular provides a manufacturing device which makes possible integrated formation by using multiple formation processes which make it possible to connect a body part which comprises the articulated part of a doll, the leg parts, the arm parts and other main component parts.

#### **[Description of the Prior Art]**

Prior-art devices for manufacturing dolls have formed parts to split the front and back as well as the left and right sides by forming the doll's body part, leg parts, arm parts and other component parts using a synthetic resin. These parts were assembled by using respective screw catches using manual assembly steps. The indicated articulated parts were formed by connecting the mutual components using rivets and the like so that the parts could rotate freely.

#### **[Problems Which the Present Invention Attempts to Resolve]**

In the prior-art manufacturing device, the doll's body part, leg parts, arm parts and other component parts were formed respectively on the front and back and on the left and right hand sides. For example, even in the most restrained design, the doll was made up of five body parts,  $5 \times 2 = 10$  leg parts and  $4 \times 2 = 8$  parts. A total of at least 39 parts was required for integral assembly of the dolls including a total of 23 parts and 8 screws for assembly and 8 rivets and others. The prior art device was defective in that a large number of parts was required. The formation parts which related to one another for the articulated parts of the doll were defective in that it was difficult to form them uniformly by contraction during the formation steps under established formation conditions and these parts were assembled manually which made the assembly process quite cumbersome. A large number of assembly steps were required and the aforementioned problems in formation ensued even if quality control was carried out for each of the steps. There were also dispersions in the finished product no matter what steps were taken and manufacturing costs were prohibitively high.

### **[Means Used to Resolve These Problems]**

The present invention has eliminated the defects in manufacturing seen in the prior-art manufacturing device and disposes multiple formation dies, with indicated angles in between, respectively on concentric circles centered around a rotation shaft. It forms the required dies at positions for the corresponding parts used to make up the respective articulated parts according to a predetermined formation sequence on the respective formation dies. It retains part of a runner for the parts formed between a core side which makes up these formation dies and a cavity side. It disposes a mounted stripper in the shaft direction of the aforementioned rotation shaft used to move to the formation die in the following formation sequence so that it can slide and rotate freely.

### **[Practical Embodiment of the Invention]**

Next, we shall describe a practical embodiment of the present invention referring to the following figures. Figure 7 and Figure 6 are dolls to be manufactured in the practical embodiment of the present invention. This doll is made up of a body part 10, leg parts 20 and arm parts 30 as the main component parts which comprise the articulated parts. The body part 10 is made up of a head part 11, a chest part 12 and a waist part 13.

To explain the manufacturing steps for one leg part 20 as indicated in Figure 5, a shaft receiving member 21 which is connected to the runner 1a as indicated in Figure 5A in the first manufacturing step and makes shaft 21a protrude is used for mounting on the shaft receiving part 14 on the aforementioned back part 13. A foot part 22 which is provided with a protruding shaft 22a which is a member for one side which makes up the articulated part forms the reinforcement parts 23 and 24. Next, in the second formation step, an intermediate part 26 is inserted which is provided with (1) an intermediate part 25 which is joined to the runner 1b, as indicated in Figure B, and which encapsulates and retains the aforementioned shaft member 21 so that it can rotate freely and has a protruding shaft 25a on the other side; and (2) an intermediate part 26 which encapsulates and retains the aforementioned protruding shaft 22a so that it can rotate freely and which is provided with a protruding shaft 26a on the other side. It forms a [one character illegible] which is provided with protruding shafts 27a and 27b which are one member which makes up the articulated part of the [one character illegible] part. Next, in the third formation step, it is formed to make an integral piece which is provided with (1) a shaft receiving member 28 which encapsulates and retains the aforementioned protruding shaft 25a and protruding shaft 27a so that it can rotate freely; and (2) protruding shaft 22a and protruding shaft 27b and forms an integral piece by inserting shaft receiving side member 29 which encapsulates and retains these shafts so that it can rotate freely, as indicated in Figure C.

The component parts in the second formation step which serve as the latter sequence in this formation step have a melting point which is lower than that of the formation materials used in the first formation step and are formed using a formation material which has a high contraction rate. The formation parts in the third formation step which is the latter sequence have a melting point which is lower than that of the formation materials which are used in the second formation step which is in a prior sequence and is formed using a formation material which has a high contraction rate. The formation step which comprises this insertion formation

is carried out consecutively and continuously so that the main component parts which make up the aforementioned multiple articulated parts form an integral part.

Figure 2 is a frontal view of the important parts of the core side 2 on the formation device which is used to carry out the series of formation steps indicated above. In the figure, a first formation die 1x which is used in the aforementioned first formation step is disposed at a position x on a concentric circle which is centered on a rotation shaft 3. A second formation die 1Y which is used in the aforementioned second formation step is disposed at a position Y which rotates 120° from the same shaft 1x. A third formation die 1Z which is used in the aforementioned formation step is disposed at a position Z which rotates 120° from the same die 1Y. A die which is required at a position on the corresponding parts to make up the respective articulated parts is formed according to a predetermined formation sequence on the formation die.

Figure 1 is an exploded inclined view of the important parts of the aforementioned formation device. In the same figure, 1 is a cavity on the formation die which corresponds to the aforementioned core 2. It is used as a means for moving to the formation die which is located at the next formation sequence the parts which are formed as indicated above between the aforementioned cavity 1 and core 2 which face it. A stripper 4 is provided with the aforementioned rotation shaft 3 and retains one end of the aforementioned runner 1a so that it can rotate freely and in the shaft direction. An ejection pedestal which is provided with an ejection pin 5a is disposed on the back side of this core 2. This core 2 and this ejection pedestal 5 are mounted so that they can slide freely in the shaft direction via a spring 6b along multiple guide pins 6a which are set so they protrude onto pressing pedestal 6 which is opposite a pressing device. A hooking pawl 7 which protrudes three ways so that it can turn this at an indicated angle, that is, 120°, is disposed on the aforementioned rotation shaft 3. A guide frame 8 which retains this so that it can turn freely and which is provided with a hydraulic device 8a on one side is disposed on the outside. A half-moon shaped guide groove 8b which is used to guide to the aforementioned hooking pawl 7 an operating shaft 9 which is disposed on the piston shaft of the aforementioned hydraulic device so that it can turn freely when pressed, is formed inside the same guide frame 8.

### [Operations]

Next, we shall explain the operations for each of the formation steps which make use of the formation device mentioned previously by referring to Figure 3 and Figure 4. Here, a core 2 side adheres tightly to the cavity 1 side indicated in a of Figure 3. A part 1c which is formed in a step in the previous sequence is inserted so that it connects to runner 1a inside the die. Injection molding takes place inside the die in this state so that a portion of the part 1c in the formation step of the previous sequence is inserted and formed to make an integral part using the formation part 1d in the latter sequence. Next, the cavity 1 is detached from the core side 2, as indicated in b in the same figure. A stripper 4 and an ejection pin 5a which forms an integral piece with the ejection pedestal 5 is pressed out via the ejection pedestal 6 and the rotation shaft 3 by pressing and operating the pressing device, as indicated in c in the same figure. The aforementioned formation parts 1c and 1d are removed from the die on the core 2 side so that they form an integral piece with the aforementioned stripper 4. Next, in Figure 4d, when the stripper 4 is continuously pressed out, the ejection pin 5a becomes left behind, the stripper 4

becomes separated from the ejection pin 5a and goes into rotation mode. Next, in e in the same figure, the aforementioned hydraulic device 8a is operated and the stripper 4 is rotated at the indicated angle, that is, at  $120^\circ$ , via the aforementioned operating shaft 9, the hooking pawl 7 and the rotation shaft 3. As a result, the aforementioned formation parts 1c and 1d which are formed using the die at this position move to the formation die at the latter position while being retained on the aforementioned stripper 4. Meanwhile, the formation part 1c which has again been formed in the step in the previous sequence as was the case above is sent as the stripper 4 turns and is positioned on the same die. Next, the aforementioned pressing device moves back as indicated in f in the same figure, the stripper 4 is positioned at the core 2, the formation part in the step in the aforementioned prior sequence is guided onto the die and is [one character illegible]. Next, we shall describe the condition in a in the aforementioned Figure 3 and injection molding is carried out in the same way.

Formation is carried out continuously in each of the aforementioned formation dies by repeating the aforementioned operations. As a result, the parts formed at the formation die 1x at the position x in Figure 2 are guided to the formation die 1Y on the position Y as the aforementioned stripper 4 rotates. It is further guided to the formation die 1Z at the position Z as the stripper 4 rotates and the remaining part is inserted and formed so that it forms an integral part. Last of all, it is removed as a completed part for the main component parts which comprise the articulated parts. At the same time, each of the runners is cut away from the formation parts by using a runner excision device which is not shown in the diagrams.

#### **[Effectiveness of the Invention]**

By continuously carrying out (1) a prior sequence formation step which forms one of the members used to make up the articulated parts and others; and (2) multiple insert formation steps which form the other member which forms a pair with the previous member, as indicated above, the body part of the doll, the leg parts, the arm parts and other main component parts which comprise the articulated parts in the present embodiment of the invention can be formed to make an integral piece. When this is used, it is no longer necessary to form a great many individual parts and assemble them. The number of parts and the steps used to assemble them can be greatly reduced and the manufacturing costs can be greatly reduced.

In particular, multiple formation dies are disposed, at indicated angles, on a concentric circle which is centered on the rotation shaft. The indicated die is formed according to a predetermined formation sequence on the respective dies. A stripper is disposed so that it can slide and rotate freely in the shaft direction of the aforementioned rotation shaft. A portion of the runner for the parts which are formed at the respective positions is retained and can be moved precisely to the formation die in the next sequence by using a simple moving means which accompanies the upward and downward motions as well as the two-stage operation of the rotation shaft. This makes it possible to simplify the formation device which carries out multiple insert formations continuously. It also makes it possible to form the parts using continuously stabilized operations.

By forming multiple continuous inserts as indicated above, a completed product with continuously stable quality can be formed without any of the dispersions in the products which were caused by the deficiencies in the prior-art dies.

#### **4. Brief Explanation of Figures**

Figure 1 is an exploded inclined view of the important parts of the toy manufacturing device in a practical embodiment of the present invention. Figure 2 is a plane view of the important parts of the same formation device. Figure 3 and Figure 4 are lateral views of the important parts of the formation device which indicates how each of the parts operates in the formation steps in the same formation device. Figure 5 is an explanatory view of each of the formation steps for the leg parts in the same device. Figure 6 is a cutaway frontal view of the important parts of the doll. Figure 7 is a cutaway lateral view of the important parts of the doll.

In the figure, 1 is the cavity; 2 is the core; 3 is the rotation shaft; 4 is the stripper; 5 is the ejection pedestal; 6 is the pressing pedestal; 7 is the hooking pawl; 8 is the guide frame; 9 is the operating shaft; 1x is the first formation die; 1Y is the second formation die; 1Z is the third formation die; 1a and 1b are the runners; 10 is the body part; 20 is the leg part; and 30 is the arm part.

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**Figure 1**

**Figure 2**

**Figure 3**

**Figure 4**

**(A)**

**(B)**

**(C)**

**Figure 5**

**Figure 6**

**Figure 7**